

Important Announcements and Notes (Sep 26)

$$- \mathcal{D} = ((\vec{x}_1, y_1), \dots, (\vec{x}_n, y_n)) \in (\mathcal{X} \times \mathcal{Y})^n$$

if $\mathcal{X} = \mathbb{R}^d$ then $\vec{x}_i \in \mathcal{X}$

$$\vec{x}_1 = (x_{11}, x_{12}, \dots, x_{1d})^T, \vec{x}_n = (x_{n1}, x_{n2}, \dots, x_{nd})^T$$

- $f(\vec{x})$ where $\vec{x} \in \mathcal{X}$

$$\vec{x} = (x_1, x_2, \dots, x_d)^T$$

$$x_1 \neq \vec{x}_1, x_2 \neq \vec{x}_2$$

Important Announcements and Notes (Sep 24)

- The predictor output by the Learner will be \hat{f} from now on. $\mathcal{A}(D) = \hat{f}$
- The dataset $D = ((\vec{X}_1, Y_1), \dots, (\vec{X}_n, Y_n))$ is used by the Learner to output a predictor \hat{f}
- The predictor $\hat{f}(\vec{X})$ takes as input any $\vec{X} \in \mathcal{X}$
 \vec{X} and \vec{X}_i are different r.v.

- if $X \in \mathcal{X}$ is a r.v. then it has a distribution \mathbb{P}
- otherwise $x \in \mathcal{X}$ is an: outcome, or instance of X , or a fixed value of X

$X \in \mathcal{X}$ and $x \in \mathcal{X}$ seem the same because we are being imprecise and X is actually a special function

$\mathbb{P}(X \in E)$ is valid $\mathbb{P}(x \in E)$ is not valid

$\mathbb{E}[X]$ is valid $\mathbb{E}[x]$ is not valid

$f(X) = X^2$ is a r.v. $f(x) = x^2$ is not a r.v.

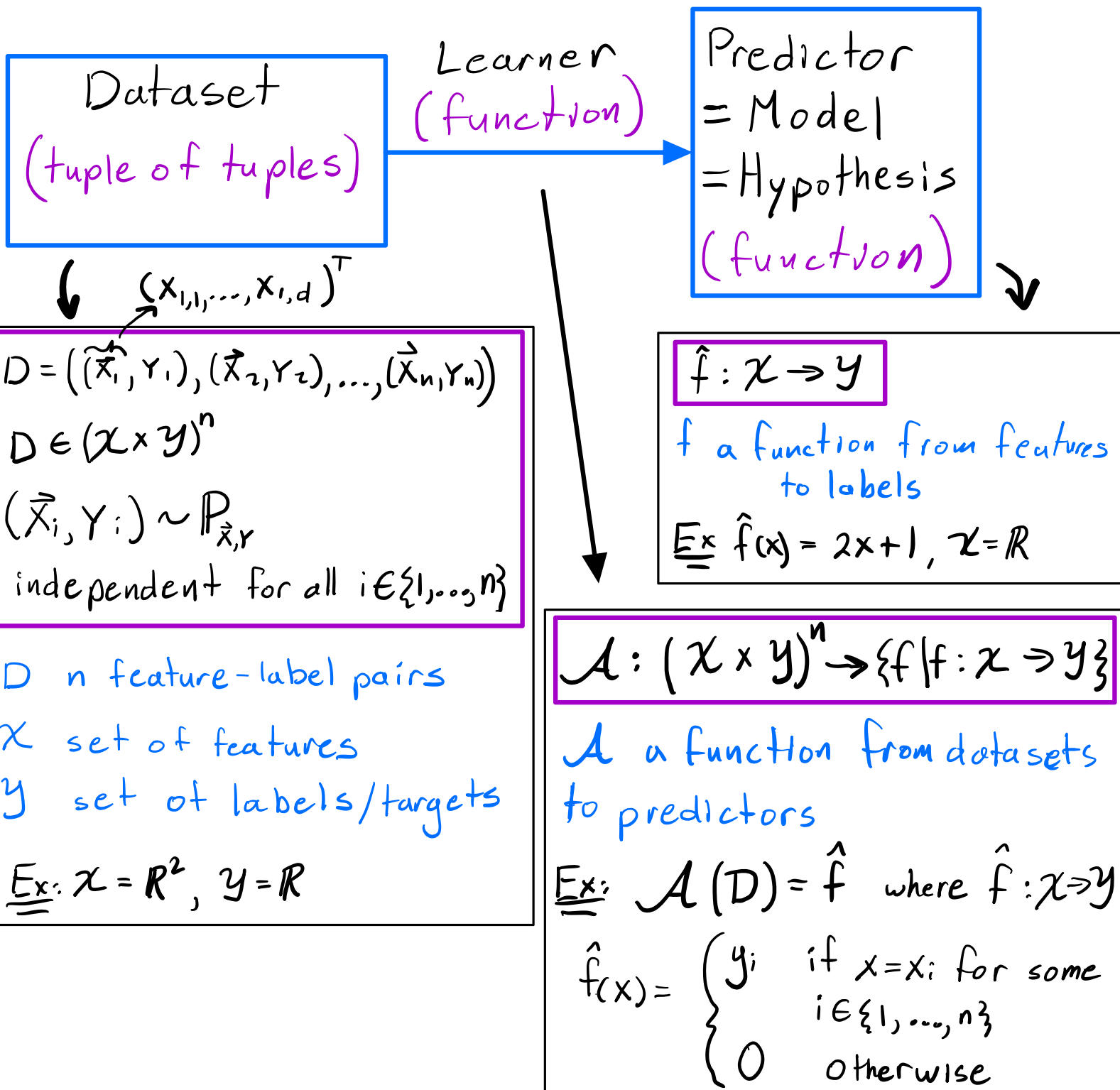
- $D \in (\mathcal{X} \times \mathcal{Y})^n$ is a r.v. with distribution \mathbb{P}_D representing the dataset
- $\mathcal{D} \in (\mathcal{X} \times \mathcal{Y})^n$ is a fixed dataset (an instance of D)

$\mathcal{A}(D)$ is a r.v. $\mathcal{A}(\mathcal{D})$ is not a r.v.

Supervised Learning: Learning from a randomly sampled batch of labeled data

What does Learning well mean?

i.e. What is the objective of Learning?



Setting:

We are given a random dataset of size n

$$D = ((\vec{X}_1, Y), \dots, (\vec{X}_n, Y_n)) \in (\mathcal{X} \times \mathcal{Y})^n$$

where $(\vec{X}_i, Y_i) \sim P_{\vec{X}, Y}$ are independent for all $i \in \{1, \dots, n\}$

\vec{X}_i feature vector

Y_i label or target

We will always assume the features are vectors.

Ex (of features and labels/targets):

$\vec{X}_i \in \mathbb{R}^3$ # of rooms, # of floors, age of a house

$Y_i \in \mathbb{R}$ price

$\vec{X}_i \in \mathbb{R}^2$ amount of chemical 1, amount of chemical 2
in a wine

$Y_i \in \{0, 1\}$ type of wine

$(1, \dots, 70)^T$
 $\vec{X}_i \in \mathbb{R}^{400}$ pixel value of a $20 \times 20 = 400$ pixel image

$Y_i \in \{\text{cat}, \text{dog}, \text{bird}\}$ type of animal

What is a feature and what is a label is a design choice. Usually a feature is info that is easy to gather. And the label is hard, which is why you want to predict it

Objective (informal):

Define a Learner $\mathcal{A}: (\mathcal{X} \times \mathcal{Y})^n \rightarrow \{f \mid f: \mathcal{X} \rightarrow \mathcal{Y}\}$

such that the predictor \hat{f} is good.

where $\mathcal{A}(D) = \hat{f}$

What is a good predictor $f: \mathcal{X} \rightarrow \mathcal{Y}$?

Forget about the dataset D for now. We just want to study a predictor f

Ex: $f(\vec{x})$ is a predictor that takes as input the # of rooms \vec{x} and outputs a price

Suppose we are given the # of rooms $\vec{x} = 2$ of a house (might not be in D)

We are not given the price $Y = 300$

what would a good predictor $f(\vec{x})$ do?

Ans: $f(2) = 300$

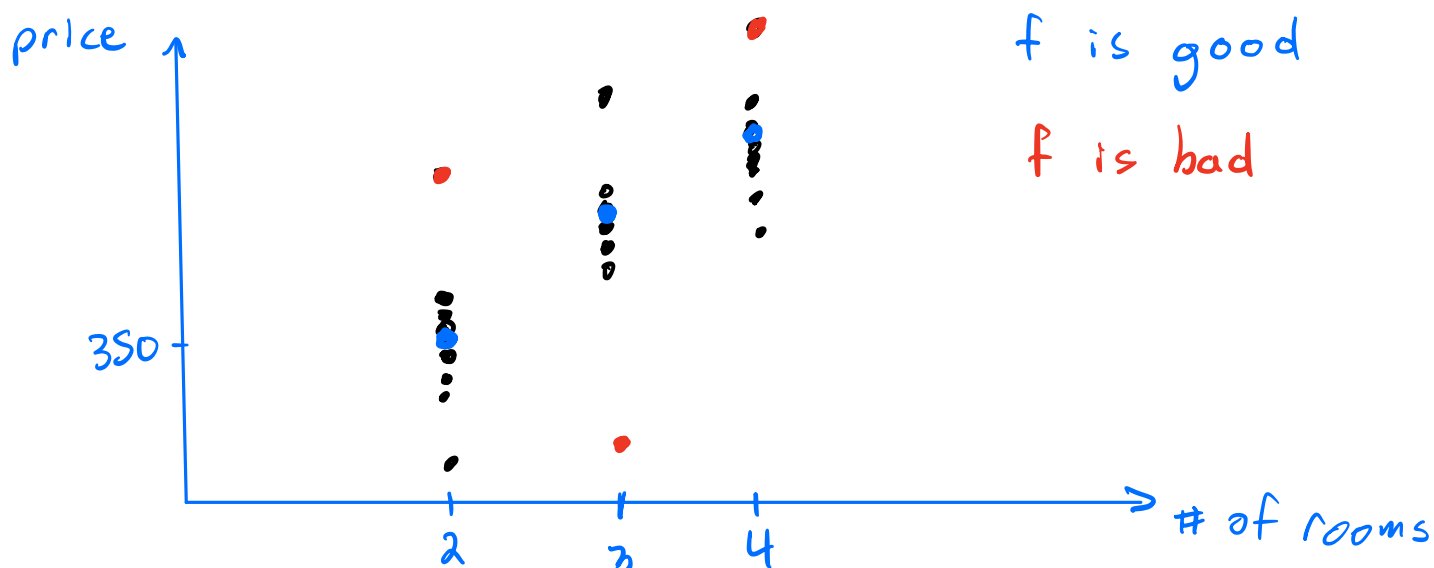
what if you were given another house?

of rooms = 2 price = 400

what would a good f be?

Ans: maybe $f(2) = \frac{400+300}{2} = 350$

what if we got even more houses?



\vec{X}, Y are random which means they can potentially be any feature-label pair

Ans: We will care about $f(\vec{X})$ being good on average

How do we measure how close $f(\vec{X})$ is to Y ?

Ans: We use a loss function $l: Y \times Y \rightarrow \mathbb{R}$

The choice of l depends on your problem

Regression: $Y \in \mathbb{Y}$ represent something with a notion of order

(Usually y is \mathbb{R} or some interval)

Ex: house prices, stock prices, energy consumption, weather prediction

We use:

$$l(f(\vec{x}), Y) = |f(\vec{x}) - Y| \quad \text{absolute loss}$$

or

$$l(f(\vec{x}), Y) = (f(\vec{x}) - Y)^2 \quad \text{squared loss}$$

A good predictor f should have a small loss l on average (expectation)

$$L(f) = \mathbb{E} [l(f(\vec{X}), Y)]$$

$$(\vec{X}, Y) \sim P_{\vec{X}, Y}$$

Ex: (squared loss)

$$p(y|x) p(x) dy dx$$

$$\mathbb{E} [l(f(\vec{X}), Y)] = \int_{\vec{x}} \int_y (f(\vec{x}) - y)^2 p(\vec{x}, y) dy d\vec{x}$$

$$= \int_{\mathcal{X}} \left(\int_{\mathcal{Y}} (f(\vec{x}) - y)^2 p(y|\vec{x}) dy \right) p(\vec{x}) dx$$

Objective (almost formal):

Define a Learner $\mathcal{A}: (\mathcal{X} \times \mathcal{Y})^n \rightarrow \{f \mid f: \mathcal{X} \rightarrow \mathcal{Y}\}$

such that $L(\hat{f})$ is small

where $\mathcal{A}(D) = \hat{f}$

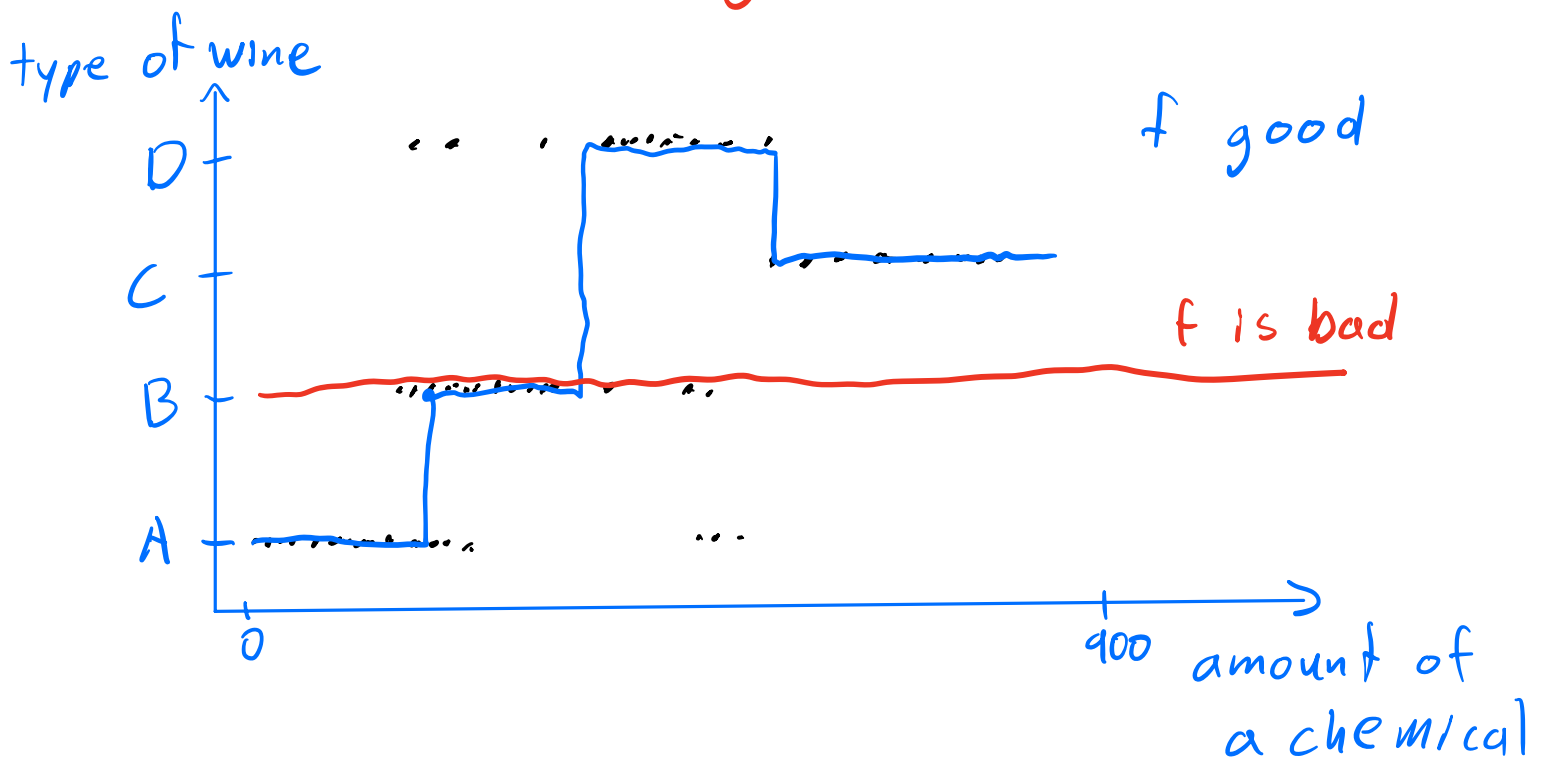
Classification: if $\mathcal{Y} \in \mathcal{Y}$ represents something without order

(Usually \mathcal{Y} is finite)

Ex: type wines, type of image, type of email, type of disease

Ex: $f(\vec{x})$ is a predictor that takes as input the amount of a chemical in a wine and outputs the type of wine

Suppose you got multiple wines, what would a good f be



for l we use:

$$l(f(\vec{x}), Y) = \begin{cases} 0 & \text{if } f(\vec{x}) = Y \\ 1 & \text{otherwise} \end{cases} \quad \text{0-1 loss}$$

Ex: $L(f)$ if we use 0-1 loss $Y = \{A, B, C, D\}$

$$\begin{aligned} L(f) &= \mathbb{E}[l(f(\vec{X}), Y)] = \int_{\mathcal{X}} \sum_{Y \in \mathcal{Y}} l(f(\vec{x}), Y) p(x, Y) dx \\ &= \int_{\mathcal{X}} \left(\sum_{Y \in \mathcal{Y}} l(f(\vec{x}), Y) p(Y|x) \right) p(x) dx \end{aligned}$$

Objective (almost formal):

Define a Learner $\mathcal{A}: (\mathcal{X} \times \mathcal{Y})^n \rightarrow \{f \mid f: \mathcal{X} \rightarrow \mathcal{Y}\}$

such that $L(\hat{f})$ is small

where $\mathcal{A}(D) = \hat{f}$

D is random! It can potentially be any dataset

If D changes then \hat{f} also changes.

Can $\mathcal{A}(D) = \hat{f}$ be good for all values of D

Ans: No you can't. There is a tradeoff.

Instead we will care about $\mathcal{A}(D) = \hat{f}$

being good on average (expectation) over datasets

$$\mathbb{E}[L(\mathcal{A}(D))]$$

Objective (formal):

Define a Learner $A: (\mathcal{X} \times \mathcal{Y})^n \rightarrow \{f \mid f: \mathcal{X} \rightarrow \mathcal{Y}\}$
such that $\mathbb{E}[L(A(D))]$ is small

First we will assume we have a fixed Dataset $D = \mathcal{D}$ (not random) and see how to define $A(D) = \hat{f}$ such that $L(\hat{f})$ is small

Our Approach:

Let f^* be the f that minimizes $L(f)$

So $A(D) = \hat{f} = f^*$

We don't know what $L(f)$ is for any f

Since we don't know $P_{\mathcal{X}, \mathcal{Y}}$

risk $L(f) = \mathbb{E}[\ell(f(\vec{X}), Y)]$

Defining $A(D)$: Empirical Risk Minimization (ERM)

Estimation:

Use D to estimate $L(f)$ for all $f \in \mathcal{F} \subset \{f | f: \mathcal{X} \rightarrow \mathcal{Y}\}$
call the estimate $\hat{L}(f)$

Optimization:

pick \hat{f} to be the $f \in \mathcal{F}$ that minimizes $\hat{L}(f)$

\nwarrow
Function class

Ex: Let \mathcal{F} be all linear functions
ERM picks the line that best fits the data

